

A coupled geo-spatial energy-air quality assessment model for the Grand Duchy of Luxembourg

L. Drouet, D. Zachary, U. Leopold, L. Aleluia

Resource Centre for Environmental Technologies,
Public Research Centre Henri Tudor,
Esch-sur-Alzette.

July 12, 2010

Problem definition

Integration of the models

Optimization

Results and perspectives

Rationale

The control and mitigation of local air pollution (NO_x , VOC, O_3) in urban region is an important problem that can benefit from an integrated approach.

Objective

To couple two models:

- ▶ an energy model which optimizes the energy system;
- ▶ an air quality model which simulates ozone episodes, and to perform a cost-benefit assessment.

$$\min_{\bar{\mathbf{e}}, \mathbf{p}} \{ \gamma(\bar{\mathbf{e}}) + \mathcal{V}(\mathbf{p}) : \text{AOT}(\bar{\mathbf{e}}) - \mathbf{p} \leq 0 \}$$

- ▶ $\gamma(\bar{\mathbf{e}})$: Energy system cost function (euros)
- ▶ $\mathcal{V}(\mathbf{p})$: Impact cost function
- ▶ $\text{AOT}(\bar{\mathbf{e}})$: AOT level function

- ▶ $\bar{\mathbf{e}}$: sectoral emissions (kt)
- ▶ \mathbf{p} : AOT level

- ▶ ETEM model (<http://www.ordecsys.com>)
- ▶ Implementation of MARKAL/TIMES in GMPL (LP)
- ▶ Energy system of Luxembourg ($\sim 100'000$ rows/columns)
- ▶ Time horizon: 9 periods of 5 years (2005–2050)
- ▶ Minimize the total discounted energy cost s.t.
 - ▶ the demands in energy services are satisfied,
 - ▶ the commodity flows balance is respected;

$$\min_{\mathbf{x}} \{ \mathbf{c}'\mathbf{x} \mid \mathbf{Ax} = \mathbf{b}, \mathbf{x} \geq 0 \}$$

Emissions are computed using stoichiometric coefficients \mathbf{s} :

$$\mathbf{s}'\mathbf{x} = \mathbf{e}.$$

Sectoral emission $\bar{\mathbf{e}}$ constrain the model:

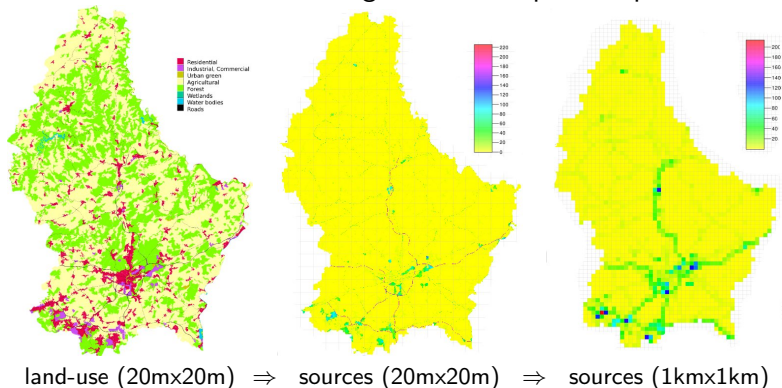
$$\gamma(\bar{\mathbf{e}}) = \min_{\mathbf{x}} \{ \mathbf{c}'\mathbf{x} \mid \mathbf{A}\mathbf{x} = \mathbf{b}, \mathbf{s}'\mathbf{x} = \mathbf{e} \leq \bar{\mathbf{e}}, \mathbf{x} \geq 0 \},$$

By construction, dual values of the added constraints define a subgradient $\frac{d\gamma(\bar{\mathbf{e}})}{d\bar{\mathbf{e}}}$.

Calculation time using GLPK solver

ETEM < 1 min

Sectoral emissions \bar{e} are distributed over space and time to provide emissions rates at sources using land-use maps and spots.



$$\bar{e} = \int_{S \times T} \mathbf{E}(t, s) ds dt$$

AYLTP is a fast air quality calculator based on

- ▶ AUSTAL2000: lagrangian transport model
- ▶ O₃ photochemical reactions: lookup table generated from OZIPR
- ▶ Input: Emissions rates at sources $\mathbf{E}(t, s)$
- ▶ Output: O₃ concentration $\mathbf{C}_{O_3}(t, s)$

AOT: Average Over Threshold (60 ppb)

$$\text{AOT}(\bar{\mathbf{e}}) = \frac{1}{|S|} \frac{1}{t} \int_{S \times T} \mathbf{C}_{\text{O}_3}(t, s; \bar{\mathbf{e}}) ds dt$$

Calculation time

Emission allocation + AYLTP + AOT calculation = 5 min

Disability adjusted life years (DALY) due to 1 ppb of ozone:

$$\text{DALY} = \text{imp}_{O_3} \times \frac{m_{O_3}}{V_{\text{air}}} \times \text{air} \times \text{nbdays} \times \text{expos} \times 10^{-9}$$

Monetarise the DALY using budget constraint:

$$\mathcal{V}(\mathbf{p}) = \mathbf{p} \times \text{pop} \times \text{pp} \times \text{DALY}$$

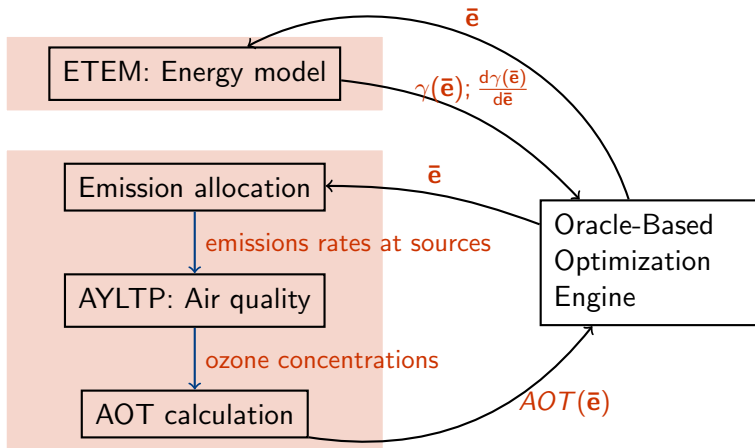
pop	population in Luxembourg in 2010	502'500
pp	potential annual economic production per capita at full well-being ^a	74'000 €/y
imp _{O₃}	ozone impact factor ^b	0.31 y/kgO ₃
air	daily breathing air of a person	10'800 L
nbdays	yearly average ozone episode duration	10 days
expos	daily exposure duration to ozone	0.25
V _{air}	volume of 1 mole of air (20°C, 1015 hpa)	24 L/mol
m _{O₃}	ozone molar mass	48 g/mol

^a(Weidema, 2009), ^b(Goedkoop, 2008)

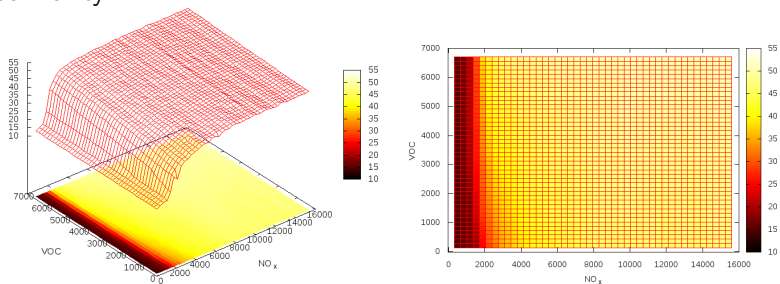
Implementation of an oracle-based optimization method (Babonneau, 2006).

- ▶ Proximal-ACCPM (Vial, 2002):
 - ▶ cutting plane method
 - ▶ choose the Analytic center as the next query point
- ▶ OBOE: oracle-based optimization engine.
- ▶ Implementation in C available at COIN-OR.

1. Initialize OBOE
2. Get the query point $(\bar{\mathbf{e}}, \mathbf{p})$ in the current localization set
3. if LHS > 0
 - ▶ Compute a feasibility cut
 - ▶ value: LHS
 - ▶ subgradient: finite-differences on AOT
4. else
 - ▶ Compute an optimality cut
 - ▶ value: $\gamma(\bar{\mathbf{e}})$
 - ▶ subgradient: $\frac{d\gamma(\bar{\mathbf{e}})}{d\bar{\mathbf{e}}}$
5. go to 2., if the stopping criterion is not meet



The AOT response in function of $\bar{\mathbf{e}} = (e_{\text{NO}_x}, e_{\text{VOC}})$ is close to convexity:



- ▶ To converge, some restarts are needed (when a new cut gives an empty localization set)
- ▶ 20 iterations and 1 restart.

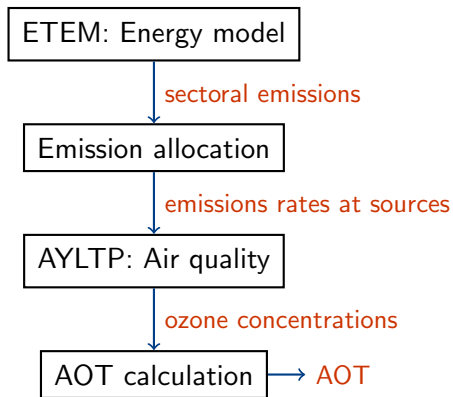
	Baseline	Cost-benefit
Energy cost (M€)	58.119	64.323
Impact cost (M€)	141.925	129.475
NO _x 2010 (t)	14 456	10 379
NO _x 2015 (t)	14 784	10 420
VOC 2010 (t)	6 570	5 388
VOC 2015 (t)	6 637	5 427
AOT 2010 (ppmb)	53	44
AOT 2020 (ppmb)	55	44

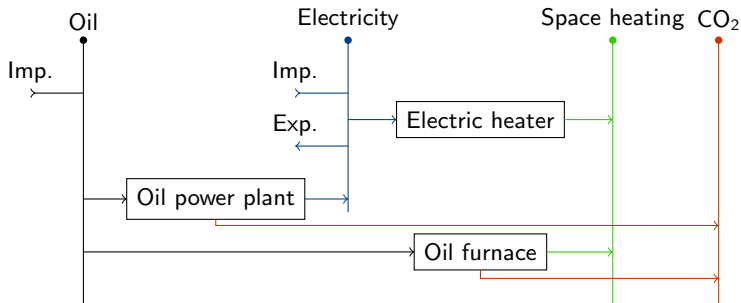
- ▶ SUNleaq project: handle spatial error in emission allocation
- ▶ Non-convexity: smooth *AOT* function using a statistical emulation.
- ▶ Spatial AOT to choose the healthier place for new residential areas.
- ▶ Calibration of the impact function



Thank you for your attention !

Contact: laurent.drouet@tudor.lu





Technologies

- ▶ ● Commodities (Fuels, energy services demands, emissions)
- ▶ \longrightarrow Commodity flows